

An Efficient Collocation Method for the Numerical Solutions of the Pantograph-Type Volterra Hammerstein Integral Equations and its Convergence Analysis

Hashem Saberi Najafi^{1*}, Sayed Arsalan Sajjadi², Hossein Aminikhah²

¹Department of Applied Mathematics, Ayandegan Institute of Higher Education, Tonekabon, Iran; hnajafi@aihe.ac.ir

²Department of Applied Mathematics and Computer Science, Faculty of Mathematical Sciences, University of Guilan, Iran.

Citation:



Saberi Najafi, H., Sajjadi, S. A., & Aminikhah, H. (2022). An efficient collocation method for the numerical solutions of the pantograph-type volterra Hammerstein integral equations and its convergence analysis. *Computational algorithms and numerical dimensions*, 1(2), 61-71.

Received: 27/11/2021

Reviewed: 19/01/2022

Revised: 14/02/2022

Accept: 24/04/2022

Abstract

In this work, we consider a collocation method for solving the pantograph-type Volterra Hammerstein integral equations based on the first kind Chebyshev polynomials. We use the Lagrange interpolating polynomial to approximate the solution. The convergence of the presented method has been analyzed by over estimating for error. Finally, some illustrative examples are given to test the accuracy of the method. The presented method is compared with the Legendre Tau method.

Keywords: Numerical solution, Collocation method, Pantograph-type, Volterra Hammerstein integral equations, Convergence analysis.

1 | Introduction

This paper aims to obtain the exact approximations by collocation method based on the first kind Chebyshev polynomials for solutions of the following pantograph Volterra Hammerstein integral equations.

$$z(s) = g(s) + \int_0^{qs} R(t,s)G(t,z(t))dt, \quad 0 < q < 1, \quad s \in [0,1]. \quad (1)$$

Where $g(s)$, $R(s,t)$ and $G(t,z(t))$ are smooth functions on their domains. We assume that the function $G(t,z(t))$ satisfies in the Lipschitz condition with respect to the second variable.

These equations appear in many branches of science such as control theory, biology, ecology and etc [1]-[7]. Several methods have been proposed to solve the integral equations in [8]-[11], [5], [12]-[16], [6], [17]-[26]. Ansari and Mokhtary [27] presented the Legendre Tau method for solving Eq. (1) and



Licensee
Computational
Algorithms and
Numerical Dimensions.

This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<http://creativecommons.org/licenses/by/4.0>).



Corresponding Author: hnajafi@aihe.ac.ir



<https://doi.org/10.22105/cand.2022.153956>

discussed applying the spectral methods to obtain a reliable numerical solution for Eq. (1) according to the well-known existence and uniqueness theorems in [27].

Here, we approximate the solution of Eq. (1) using the Lagrange interpolating polynomial. We consider a collocation method based on the first kind Chebyshev polynomials for solving Eq. (1) and get a non-linear system that can be solved by Newton method to obtain the solutions at the grid points. In order to use the theory of orthogonal polynomials, we transform the Eq. (1) to $[-1,1]$ and analyze the convergence of the presented method. Some numerical examples prepared to test the efficiency and accuracy of the proposed method. We compare the numerical results of the presented method with the Legendre Tau method in [27].

2 | Algorithm of the Method

The first kind of Chebyshev polynomials $T_N(s)$ are orthogonal at $[-1,1]$ with respect to the weight function $w(s) = (1 - s^2)^{-1/2}$ and are defined by [28]:

$$T_N(s) = \cos(N \cos^{-1}(s)).$$

All Chebyshev polynomials $T_N(s)$ can be generated by the following recursion relation

$$T_N(s) = 2sT_{N-1}(s) - T_{N-2}(s), \quad N = 2, 3, \dots$$

With

$$T_0(s) = 1, T_1(s) = s.$$

The Gauss quadrature formula

$$\int_{-1}^1 f(s)w(s)ds \approx \sum_{k=0}^N f(s_k)w_k.$$

is exact for any polynomial of degree $\leq 2N + 1$.

Now, in order to use the theory of orthogonal Chebyshev polynomials, applying the following change of variable

$$\begin{cases} t = \frac{q}{2}\eta + \frac{q}{2}, & -1 \leq \eta \leq \zeta, \quad 0 < q < 1, \\ s = \frac{1}{2}\zeta + \frac{1}{2}, & -1 \leq \zeta \leq 1. \end{cases}$$

For Eq. (1), we have

$$\tilde{z}(\zeta) = \tilde{g}(\zeta) + \int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta, \quad -1 \leq \zeta \leq 1. \quad (2)$$

Where

$$\begin{cases} \tilde{z}(\zeta) = z\left(\frac{1}{2}\zeta + \frac{1}{2}\right), \\ \tilde{g}(\zeta) = g\left(\frac{1}{2}\zeta + \frac{1}{2}\right), \\ \tilde{R}(\zeta, \eta) = \frac{q}{2}R\left(\frac{1}{2}\zeta + \frac{1}{2}, \frac{q}{2}\eta + \frac{q}{2}\right), \\ \tilde{G}(\eta, \tilde{z}(\eta)) = G\left(\frac{q}{2}\eta + \frac{q}{2}, z\left(\frac{q}{2}\eta + \frac{q}{2}\right)\right). \end{cases}$$

Using the Lagrange interpolating polynomial, we can approximate $\tilde{z}(\zeta)$ as



$$I_N^C(\tilde{z}(\zeta)) = \sum_{j=0}^N l_j(\zeta) \tilde{z}(s_j). \quad (3)$$

Where

$$l_i(\eta) = \prod_{j=0, j \neq i}^N \frac{\eta - s_j}{s_i - s_j}, \quad i = 0(1)N.$$

And $\{s_j = -\cos\left(\frac{(2j+1)\pi}{2N+2}\right)\}_{j=0}^N$ are the Chebyshev Gauss quadrature points. Also, from Eq. (3), we can write

$$\tilde{G}\left(\zeta, I_N^C(\tilde{z}(\zeta))\right) = \sum_{j=0}^N l_j(\zeta) \tilde{G}\left(s_j, \tilde{z}(s_j)\right). \quad (4)$$

Now, collocating the nodes s_i , $i = 0(1)N$, in Eq. (2), we have

$$\tilde{z}(s_i) = \tilde{g}(s_i) + \int_{-1}^{s_i} \tilde{R}(s_i, \eta) \tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) d\eta, \quad i = 0(1)N. \quad (5)$$

Solving the non-linear system (5) by the Newton method, we get the values of $\tilde{z}(s_j)$. Substituting these values into Eq. (3), the values of $I_N^C(\tilde{z}(\zeta))$ are obtained, for all $\zeta \in [-1, 1]$.

3 | Convergence Analysis

In this section, using some useful inequalities and lemmas from [29], [30], we will try to determine over estimate for $\|I_N^C(\tilde{z}(\zeta)) - \tilde{z}(\zeta)\|_{L_{w^2}^2(-1,1)}$.

Theorem 1. Assume that $I_N^C(\tilde{z}(\zeta))$ is the spectral collocation solution of Eq. (2) given by Eq. (3). If the functions $\tilde{g}(\zeta)$, $\tilde{R}(\zeta, \eta)$ and $\tilde{G}(\eta, \tilde{z}(\eta))$ are sufficiently smooth and $\tilde{G}(\eta, \tilde{z}(\eta))$ satisfies in the Lipschitz condition with respect to the second variable and $e(\zeta) = I_N^C(\tilde{z}(\zeta)) - \tilde{z}(\zeta)$, then we have

$$\|e\|_{L_{w^2}^2(-1,1)} \leq CN^{-m} \left(\|\tilde{g}\|_{H_w^{m,N}(-1,1)} + L \|\tilde{z}\|_{H_w^{m,N}(-1,1)} \right) + CN^{-1} \left(\|\tilde{G}\| + N^{-m} L \|\tilde{z}\|_{H_w^{m,N}(-1,1)} \right). \quad (6)$$

Proof. The Eq. (5) can be written as follows

$$\begin{aligned} \tilde{z}(s_i) = \tilde{g}(s_i) &+ \int_{-1}^{s_i} \tilde{R}(s_i, \eta) \tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) d\eta + \int_{-1}^{s_i} \tilde{R}(s_i, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta \\ &- \int_{-1}^{s_i} \tilde{R}(s_i, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta. \end{aligned} \quad (7)$$

Multiplying Eq. (7) by $l_j(\zeta)$ and sum up from 0 to N , we have

$$\begin{aligned} I_N^C(\tilde{z}(\zeta)) &= I_N^C(\tilde{g}(\zeta)) \\ &+ I_N^C\left(\int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta\right) \\ &+ I_N^C\left(\int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta\right). \end{aligned} \quad (8)$$

Subtracting Eq. (8) from the Eq. (2), we have

$$e(\zeta) = L_2 + I_N^C\left(\int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta\right) + L_3. \quad (9)$$

Where

$$\begin{cases} L_2 = I_N^C(\tilde{g}(\zeta)) - \tilde{g}(\zeta), \\ L_3 = I_N^C\left(\int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta\right) - \int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \tilde{G}(\eta, \tilde{z}(\eta)) d\eta. \end{cases}$$

The Eq. (9) can be rewritten as follows

$$e(\zeta) = L_2 + \int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta + L_3 + L_4. \quad (10)$$

Where

$$\begin{aligned} L_4 = I_N^C & \left(\int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta \right) \\ & - \int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta. \end{aligned}$$

To simplicity, in the following the notation $\|\cdot\|$ has been used instead of $\|\cdot\|_{L_w^2(-1,1)}$. Now, from the Eq. (10), we have

$$\|e(\zeta)\| \leq \|L_2\| + \left\| \int_{-1}^{\zeta} \tilde{R}(\zeta, \eta) \left(\tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right) d\eta \right\| + \|L_3\| + \|L_4\|. \quad (11)$$

Now, in order to determine over estimate for error, we should find the over bound for right hand side of the inequality Eq. (11) term by term.

Using inequality (5.5.22) from [29], we have

$$\|L_2\| \leq CN^{-m} |\tilde{g}|_{H_W^{m,N}(-1,1)}. \quad (12)$$

Where

$$|\tilde{g}|_{H_W^{m,N}(-1,1)} = \left(\sum_{k=\min(m,N+1)}^m \|\tilde{g}^{(k)}\|^2 \right)^{1/2}. \quad (13)$$

For Eq. (12), using Eq. (13) with $m = 1$ and Lemma 3.8 from [30], we have

$$\begin{aligned} \|L_3\| & \leq CN^{-1} \left(\left\| \int_{-1}^{\zeta} \frac{\partial(\tilde{R}(\zeta, \eta))}{\partial \zeta} \tilde{G}(\eta, \tilde{z}(\eta)) d\eta + \tilde{R}(\zeta, \zeta) \tilde{G}(\zeta, \tilde{z}(\zeta)) \right\| \right) \\ & \leq CN^{-1} \left(\left\| \int_{-1}^{\zeta} \frac{\partial(\tilde{R}(\zeta, \eta))}{\partial \zeta} \tilde{G}(\eta, \tilde{z}(\eta)) d\eta \right\| + \|\tilde{R}(\zeta, \zeta)\| \|\tilde{G}(\zeta, \tilde{z}(\zeta))\| \right) \\ & \leq CN^{-1} (C \|\tilde{G}(\eta, \tilde{z}(\eta))\| + \|\tilde{R}(\zeta, \zeta)\| \|\tilde{G}(\zeta, \tilde{z}(\zeta))\|). \end{aligned} \quad (14)$$

Thus, from Eq. (14), we have

$$\|L_3\| \leq CN^{-1} \|\tilde{G}\|. \quad (15)$$

To find over bound for $\|L_4\|$, similar to process of obtaining Eq. (15), we have

$$\|L_4\| \leq CN^{-1} \left\| \tilde{G}\left(\eta, I_N^C(\tilde{z}(\eta))\right) - \tilde{G}(\eta, \tilde{z}(\eta)) \right\|. \quad (16)$$

Since $\tilde{G}(\eta, \tilde{z}(\eta))$ satisfies in the Lipschitz condition with respect to the second variable. Thereby from Eq. (16), we have

$$\|L_4\| \leq CN^{-1} L \|e\|. \quad (17)$$

Where L is the Lipschitz constant. Now, applying (5.5.22) from [29] for Eq. (17), we have

$$\|L_4\| \leq CN^{-1-m} L |\tilde{z}|_{H_W^{m,N}(-1,1)}.$$



Using Lipschitz condition and (5.5.22) from [29], we have

$$\left\| \int_{-1}^{\zeta} \widetilde{R}(\zeta, \eta) \left(\widetilde{G}(\eta, I_N^C(\widetilde{z}(\eta))) - \widetilde{G}(\eta, \widetilde{z}(\eta)) \right) d\eta \right\| \leq CLN^{-m} |\widetilde{z}|_{H_W^{m;N}(-1,1)}.$$

Combining the above estimates with Eq. (11) leads to the intended error estimate Eq. (6).

4 | Numerical Results

In this section, we use the proposed method for solving some numerical examples to test the accuracy of the method. We get the numerical results by Wolfram Mathematica 12.2. The presented method has been compared with the Legendre Tau method in [27]. For simplicity, we use the notation $\|\cdot\|$ instead of $\|\cdot\|_{L_w^2}$.

Example 1. Consider the following pantograph-type Volterra Hammerstein integral equation [27]

$$z(s) = g(s) + \int_0^{qs} R(t, s) G(t, z(t)) dt, \quad s \in [0, 1].$$

Where

$$\begin{cases} g(s) = -\frac{1}{4} \exp(s)(s - \sin(s)) + \tan(s), \\ q = \frac{1}{2}, \frac{7}{10}, \\ R(s, t) = \exp(s) \cos^2(t), \\ G(t, z(t)) = z^2(t). \end{cases}$$

And the exact solution is $z(s) = \tan(s)$. The function $G(t, z(t))$ satisfies in the Lipschitz condition with respect to the second variable.

Table 1 contains a comparison of the L^2 -norms of the error function between the presented method and the Legendre Tau method in [27] for Example 1 with $q = \frac{1}{2}$. Figs. 1 and 2 show the plots of the obtained errors $|z - I_N^C(z)|$ by the presented method in Example 1 for $N = 8$ and $N = 32$, respectively, with $q = \frac{1}{2}$. Fig. 9 shows tending $\|z - I_N^C(z)\|$ to zero by increasing N in Example 1 with $q = \frac{1}{2}$.

Table 2 contains the obtained errors $\|z - I_N^C(z)\|$ by the presented method for Example 1 with $q = \frac{7}{10}$. Figs. 3 and 4 show the plots of the obtained errors $|z - I_N^C(z)|$ by the presented method in Example 1 for $N = 8$ and $N = 32$, respectively, with $q = \frac{7}{10}$. Fig. 10 shows tending $\|z - I_N^C(z)\|$ to zero by increasing N in Example 1 with $q = \frac{7}{10}$.

Example 2. Consider the following pantograph-type Volterra Hammerstein integral equation [27]

$$z(s) = g(s) + \int_0^{qs} R(t, s) G(t, z(t)) dt, \quad s \in [0, 1].$$

Where

$$\begin{cases} g(s) = \frac{1}{8} \left(4 \cosh\left(\frac{3s}{4}\right) - 4 \cosh(s) + s \sinh\left(\frac{3s}{4}\right) \right) + \sinh^{-1}\left(\frac{s}{2}\right), \\ q = \frac{1}{4}, \\ R(s, t) = \cosh(s - t), \\ G(t, z(t)) = \sinh(z(t)). \end{cases}$$

And the exact solution is $z(s) = \sinh^{-1}\left(\frac{s}{2}\right)$. The function $G(t, z(t))$ satisfies in the Lipschitz condition with respect to the second variable.

Table 3 contains a comparison of the L^2 -norms of the error function between the presented method and the Legendre Tau method in [27] for *Example 2*. Figs. 5 and 6 show the plots of the obtained errors $|z - I_N^C(z)|$ by the presented method for *Example 2* with $N = 8$ and $N = 32$, respectively. Fig. 11 shows tending $\|z - I_N^C(z)\|$ to zero by increasing N in *Example 2*.

Example 3. Consider the following pantograph-type Volterra Hammerstein integral equation

$$z(s) = g(s) + \int_0^{qs} R(t, s)G(t, z(t))dt, \quad s \in [0, 1].$$

Where

$$\begin{cases} g(s) = 2.125 - 0.42s^2 + \cos\left(\frac{s}{4}\right) - 2\cos\left(\frac{2s}{5}\right) - 0.125\cos\left(\frac{4s}{5}\right) - 1.8s\sin\left(\frac{2s}{5}\right) - \\ 0.225s\sin\left(\frac{4s}{5}\right), \\ q = \frac{8}{10}, \\ R(s, t) = s + t, \\ G(t, z(t)) = z(t)^4. \end{cases}$$

And the exact solution is $z(s) = \cos\left(\frac{s}{4}\right)$. The function $G(t, z(t))$ satisfies in the Lipschitz condition with respect to the second variable.

Table 4 contains the obtained errors $\|z - I_N^C(z)\|$ by the presented method for *Example 3*. Figs. 7 and 8 show the plots of the obtained errors $|z - I_N^C(z)|$ by the presented method in *Example 3* for $N = 8$ and $N = 32$, respectively. Fig. 12 shows tending $\|z - I_N^C(z)\|$ to zero by increasing N in *Example 3*.

Table 1. Comparison of the presented method and the Legendre Tau method in [27] for example 1 with $q = \frac{1}{2}$.

N	$\ z - I_N^C(z)\ $ for the Presented Method	$\ z - I_N^C(z)\ $ for the Legendre Tau Method
2	4.99e -02	---
4	1.97e -03	6.17e - 02
8	1.19e -05	7.96e - 03
16	2.03e -10	1.62e - 04
32	1.29e -15	8.66e - 08
64	8.66e -16	3.31e - 14

Table 2. The obtained errors $\|z - I_N^C(z)\|$ by the presented method for example 1 with $q = \frac{7}{10}$.

N	2	4	8	16	32	64
$\ z - I_N^C(z)\ $	6.01e -02	1.50e - 03	1.23e - 05	1.97e - 10	8.77e - 16	1.74e - 16

Table 3. Comparison of the presented method and the Legendre Tau method in [27] for example 2.

N	$\ z - I_N^C(z)\ $ for the Presented Method	$\ z - I_N^C(z)\ $ for the Legendre Tau Method
2	4.23e -13	---
4	1.69e -14	6.29e - 04
8	8.49e -16	1.17e - 05
16	5.69e -16	1.24e - 08
32	3.95e -16	4.94e - 14
64	1.04e -16	---



Table 4. The obtained errors $\|z - I_N^C(z)\|$ by the presented method for example 3.

N	2	4	8	16	32	64
$\ z - I_N^C(z)\ $	2.85e-04	1.29e-07	1.35e-13	8.30e-14	1.62e-15	1.01e-15

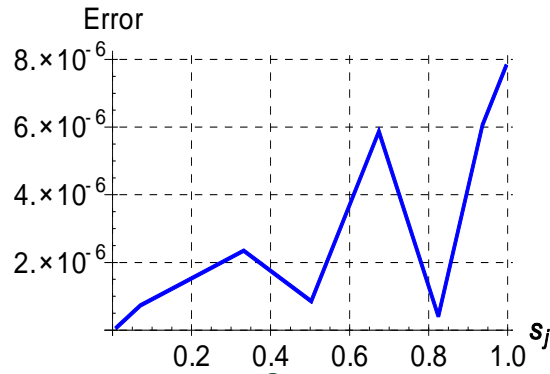


Fig. 1. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 8$ in example 1 with $q = \frac{1}{2}$.

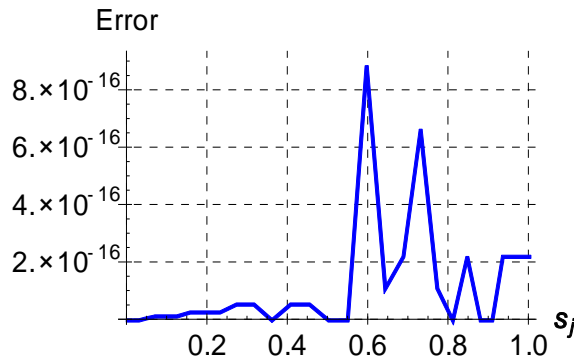


Fig. 2. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 32$ in example 1 with $q = \frac{1}{2}$.

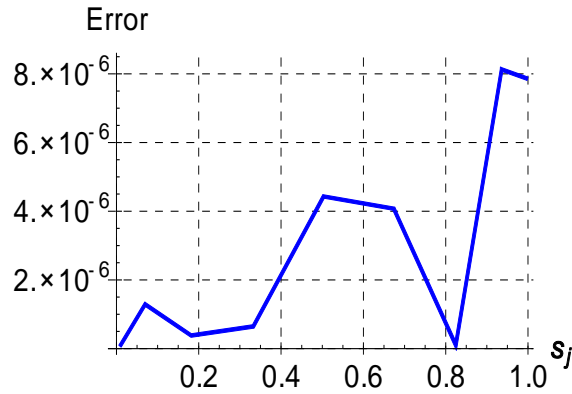


Fig. 3. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 8$ in example 1 with $q = \frac{7}{10}$.

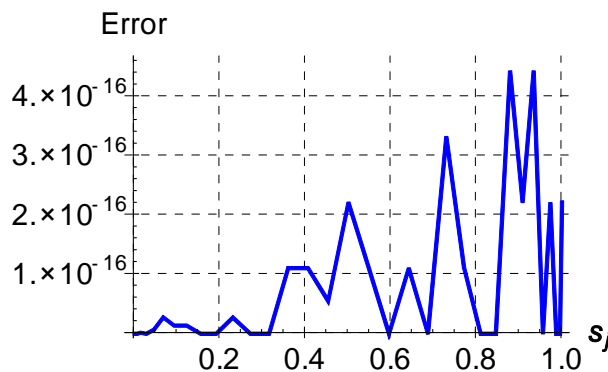


Fig. 4. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 32$ in example 1
with $q = \frac{7}{10}$.

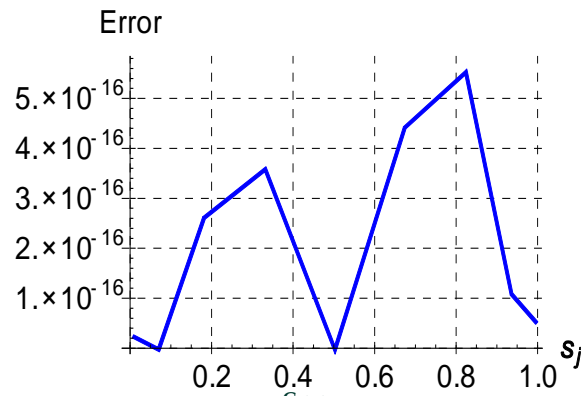


Fig. 5. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 8$ for example 2.

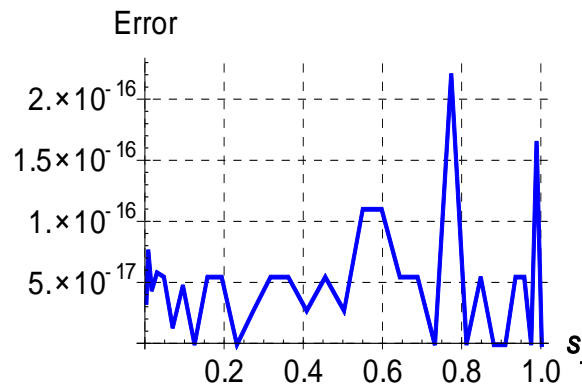


Fig. 6. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 32$ for example 2.

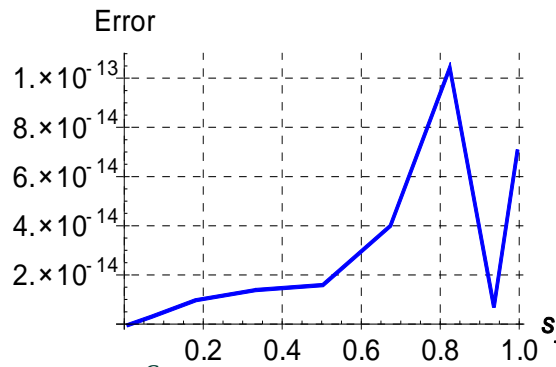


Fig. 7. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 8$ for example 3.

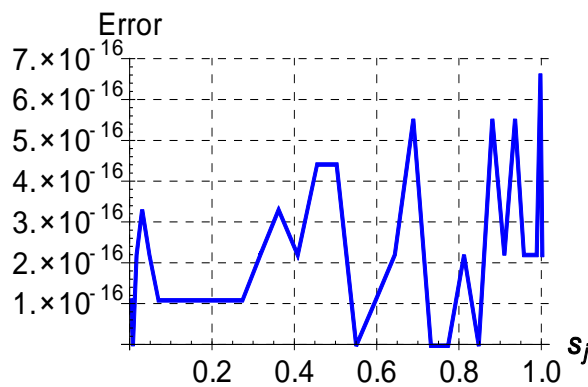


Fig. 8. Plot of the obtained errors $|z - I_N^C(z)|$ by the presented method for $N = 32$ for example 3.



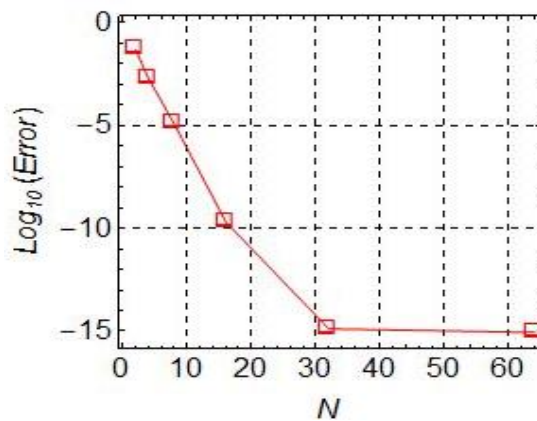


Fig. 9. Graph of tending $\|z - I_N^C(z)\|$ to zero by increasing N in example 1 with $q = \frac{1}{2}$.

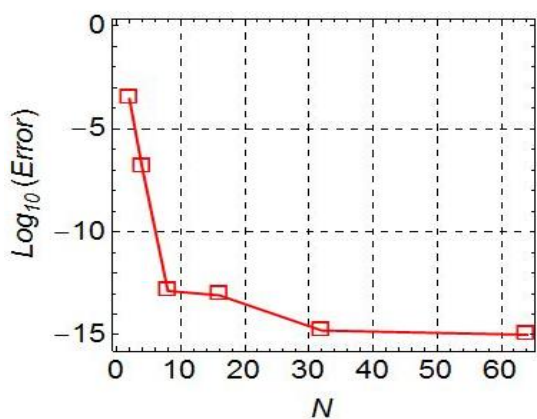


Fig. 10. Graph of tending $\|z - I_N^C(z)\|$ to zero by increasing N in example 1 with $q = \frac{7}{10}$.

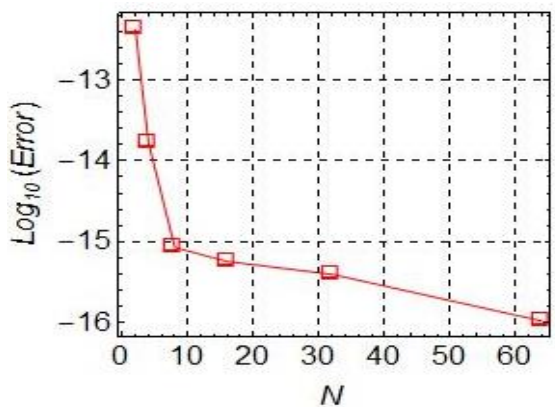


Fig. 11. Graph of tending $\|z - I_N^C(z)\|$ to zero by increasing N in example 2.

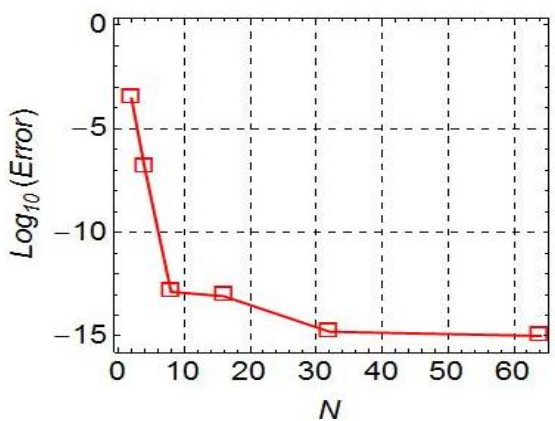


Fig. 12. Graph of tending $\|z - I_N^C(z)\|$ to zero by increasing N in example 3.

In this work, we applied a spectral collocation method to the numerical solution of the pantograph-type Volterra Hammerstein integral equations based on the first kind Chebyshev polynomials. We employed the Lagrange interpolating polynomial to approximate the solution.

The convergence of the presented method is analyzed. Some numerical examples are prepared to test the accuracy of the proposed method. We observed that the proposed method is more accurate than Legendre Tau method in [27]. The other polynomials can be used for solving these equations such as Chelyshkov polynomials, Legendre polynomials, other kinds of Chebyshev polynomials, and so on.

Funding

A Funding Statement is included in the metadata of each published article. The Funding Statement includes the funding information declared by the authors.

Conflicts of Interest

The authors have no conflict of interest.

References

- [1] Bellen, A., & Zennaro, M. (2013). *Numerical methods for delay differential equations*. Oxford University Press.
- [2] Iserles, A., & Liu, Y. (1994). On pantograph integro-differential equations. *The journal of integral equations and applications*, 6(2), 213-237. <https://www.jstor.org/stable/26163088>
- [3] Iserles, A., & Liu, Y. (1997). Integro-differential equations and generalized hypergeometric functions. *Journal of mathematical analysis and applications*, 208(2), 404-424. <https://doi.org/10.1006/jmaa.1997.5322>
- [4] Iserles, A., & Liu, Y. (1997). On neutral functional-differential equations with proportional delays. *Journal of mathematical analysis and applications*, 207(1), 73-95. <https://doi.org/10.1006/jmaa.1997.5262>
- [5] Ishiwata, E., & Muroya, Y. (2009). On collocation methods for delay differential and Volterra integral equations with proportional delay. *Frontiers of mathematics in China*, 4(1), 89-111. <https://doi.org/10.1007/s11464-009-0004-x>
- [6] Muroya, Y., Ishiwata, E., & Brunner, H. (2003). On the attainable order of collocation methods for pantograph integro-differential equations. *Journal of computational and applied mathematics*, 152(1-2), 347-366. [https://doi.org/10.1016/S0377-0427\(02\)00716-1](https://doi.org/10.1016/S0377-0427(02)00716-1)
- [7] Tohidi, E., Bhrawy, A. H., & Erfani, K. (2013). A collocation method based on Bernoulli operational matrix for numerical solution of generalized pantograph equation. *Applied mathematical modelling*, 37(6), 4283-4294. <https://doi.org/10.1016/j.apm.2012.09.032>
- [8] Brunner, H. (2004). *Collocation methods for Volterra integral and related functional differential equations* (Vol. 15). Cambridge University Press.
- [9] Cai, H., & Qi, J. (2016). A legendre-galerkin method for solving general volterra functional integral equations. *Numerical algorithms*, 73(4), 1159-1180. <https://doi.org/10.1007/s11075-016-0134-7>
- [10] Dönmez Demir, D., Kürkcü, Ö. K., & Sezer, M. (2021). Pell-lucas series approach for a class of fredholm-type delay integro-differential equations with variable delays. *Mathematical sciences*, 15(1), 55-64.
- [11] Ghomanjani, F., Farahi, M. H., & Pariz, N. (2017). A new approach for numerical solution of a linear system with distributed delays, volterra delay-integro-differential equations, and nonlinear Volterra-fredholm integral equation by bezier curves. *Computational and applied mathematics*, 36(3), 1349-1365. <https://doi.org/10.1007/s40314-015-0296-2>
- [12] Ali, I., Brunner, H., & Tang, T. (2009). A spectral method for pantograph-type delay differential equations and its convergence analysis. *Journal of computational mathematics*, 27(2/3), 254-265. <https://www.jstor.org/stable/43693505>



- [13] Ali, I., Brunner, H., & Tang, T. (2009). Spectral methods for pantograph-type differential and integral equations with multiple delays. *Frontiers of mathematics in China*, 4(1), 49-61. <https://doi.org/10.1007/s11464-009-0010-z>
- [14] Laeli Dastjerdi, H., & Nili Ahmadabadi, M. (2017). Moving least squares collocation method for Volterra integral equations with proportional delay. *International journal of computer mathematics*, 94(12), 2335-2347. <https://doi.org/10.1080/00207160.2017.1283024>
- [15] Mansouri, L., & Azimzadeh, Z. (2022). Numerical solution of fractional delay Volterra integro-differential equations by Bernstein polynomials. *Mathematical sciences*, 1-12. <https://doi.org/10.1007/s40096-022-00463-3>
- [16] Mokhtary, P., Moghaddam, B. P., Lopes, A. M., & Machado, J. A. (2020). A computational approach for the non-smooth solution of non-linear weakly singular Volterra integral equation with proportional delay. *Numerical algorithms*, 83(3), 987-1006. <https://doi.org/10.1007/s11075-019-00712-y>
- [17] Nili Ahmadabadi, M., & Laeli Dastjerdi, H. (2020). Numerical treatment of nonlinear Volterra integral equations of Urysohn type with proportional delay. *International journal of computer mathematics*, 97(3), 656-666. <https://doi.org/10.1080/00207160.2019.1585538>
- [18] Okeke, G. A., & Efut Ofem, A. (2022). A novel iterative scheme for solving delay differential equations and nonlinear integral equations in banach spaces. *Mathematical methods in the applied sciences*, 45(9), 5111-5134. <https://doi.org/10.1002/mma.8095>
- [19] Rahimkhani, P., Ordokhani, Y., & Babolian, E. (2017). A new operational matrix based on Bernoulli wavelets for solving fractional delay differential equations. *Numerical algorithms*, 74(1), 223-245. <https://doi.org/10.1007/s11075-016-0146-3>
- [20] Du, J., Lu, C., & Jiang, Y. (2022). Rothe's method for solving multi-term caputo-katugampola fractional delay integral diffusion equations. *Mathematical methods in the applied sciences*, 45(12), 7426-7442. <https://doi.org/10.1002/mma.8250>
- [21] Sajjadi, S. A., & Pishbin, S. (2021). Convergence analysis of the product integration method for solving the fourth kind integral equations with weakly singular kernels. *Numerical algorithms*, 86(1), 25-54. <https://doi.org/10.1007/s11075-020-00877-x>
- [22] Sajjadi, S. A., Najafi, H. S., & Aminikhah, H. (2022). An error estimation of a nyström type method for integral-algebraic equations of index-1. *Mathematical sciences*, 1-13. <https://doi.org/10.1007/s40096-022-00467-z>
- [23] Sajjadi, S. A., Najafi, H. S., & Aminikhah, H. (2022). A numerical algorithm for solving index-1 weakly singular integral-algebraic equations with non-smooth solutions. *Applicable analysis*, 1-18. <https://doi.org/10.1080/00036811.2022.2091551>
- [24] Taghizadeh, E., & Matinfar, M. (2019). Modified numerical approaches for a class of Volterra integral equations with proportional delays. *Computational and applied mathematics*, 38(2), 1-19. <https://doi.org/10.1007/s40314-019-0819-3>
- [25] Wei, Y., & Chen, Y. (2012). Legendre spectral collocation methods for pantograph Volterra delay-integro-differential equations. *Journal of scientific computing*, 53(3), 672-688. <https://doi.org/10.1007/s10915-012-9595-6>
- [26] Yüzbaşı, Ş. (2014). Laguerre approach for solving pantograph-type Volterra integro-differential equations. *Applied mathematics and computation*, 232, 1183-1199. <https://doi.org/10.1016/j.amc.2014.01.075>
- [27] Ansari, H., & Mokhtary, P. (2019). Computational Legendre tau method for Volterra Hammerstein pantograph integral equations. *Bulletin of the Iranian mathematical society*, 45(2), 475-493. <https://doi.org/10.1007/s41980-018-0144-4>
- [28] Mason, J. C., & Handscomb, D. C. (2002). *Chebyshev polynomials*. Chapman and Hall/CRC.
- [29] Canuto, C., Hussaini, M. Y., Quarteroni, A., & Zang, T. A. (2007). *Spectral methods: fundamentals in single domains*. Springer science & business media.
- [30] Chen, Y., & Tang, T. (2010). Convergence analysis of the Jacobi spectral-collocation methods for Volterra integral equations with a weakly singular kernel. *Mathematics of computation*, 79(269), 147-167. <https://www.ams.org/journals/mcom/2010-79-269/S0025-5718-09-02269-8/>